

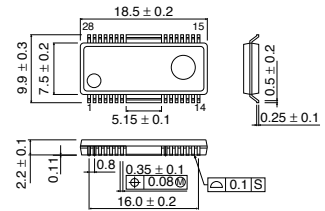
# Current feedback actuator driver

## BA5954FP/FM

### ● Description

BA5954FP/FM is an actuator driver IC for CD-ROM and DVD players. This actuator driver adopts current feedback system. This IC incorporates 2 channel actuator drivers and 2 channel motor drivers. Current phase lag influenced load inductance is little, because this type is current feedback.

### ● Dimension (Units : mm)



HSOP28 / HSOP-M28

### ● Features

- 1) Wide dynamic range  
 $V_{OM}4.0V(\text{typ.})$  at  $PreV_{CC}=12V, PV_{CC}=5V, R_L=8\Omega$
- 2) Level shift circuit built in.
- 3) Thermal-shut-down circuit built in.
- 4) Stand-by mode built in.

### ● Applications

CD/CD-ROM

### ● Absolute Maximum Ratings ( $T_a=25^\circ\text{C}$ )

| Parameter                   | Symbol               | Limits               |                      | Unit             |
|-----------------------------|----------------------|----------------------|----------------------|------------------|
| Supply voltage              | $V_{CC}, PV_{CC1/2}$ | 18                   |                      | V                |
| Power dissipation           | $P_d$                | (BA5954FP) *1<br>1.7 | (BA5954FM) *2<br>2.2 | W                |
| Operating temperature range | $T_{opr}$            | -35 ~ +85            |                      | $^\circ\text{C}$ |
| Storage temperature range   | $T_{stg}$            | -55 ~ +150           |                      | $^\circ\text{C}$ |

\* PCB (70mmx70mm,  $t=1.6\text{mm}$ ) glass epoxy mounting.

\*1 Derating :  $13.6\text{mW}/^\circ\text{C}$  for operation above  $T_a=25^\circ\text{C}$

\*2 Derating :  $17.6\text{mW}/^\circ\text{C}$  for operation above  $T_a=25^\circ\text{C}$

### ● Recommended Operating Conditions ( $T_a=25^\circ\text{C}$ )

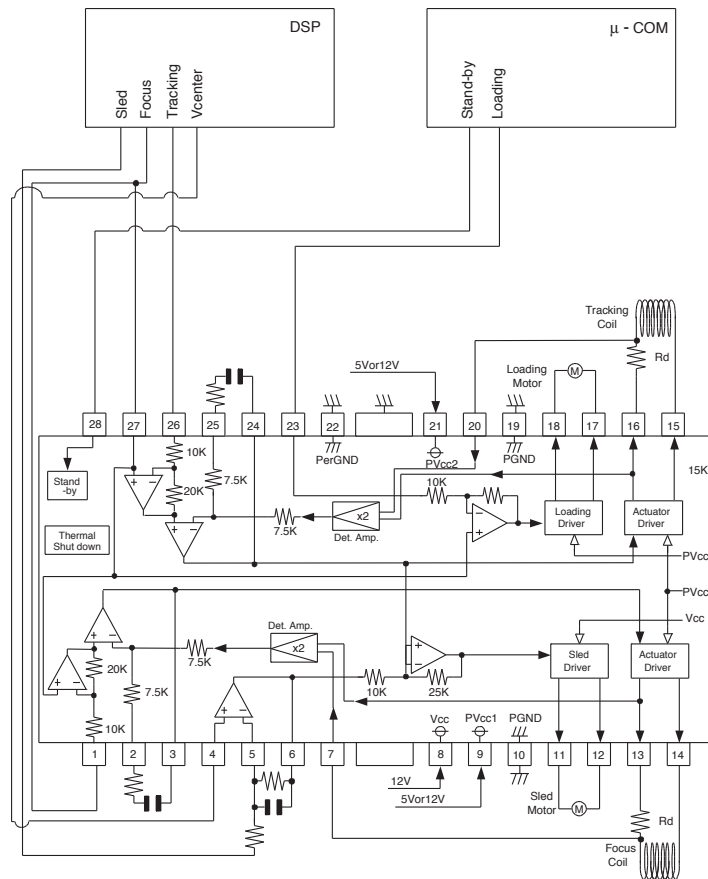
| Parameter            | Symbol     | Limits |            | Unit |
|----------------------|------------|--------|------------|------|
| Power supply voltage | $V_{CC}$   | 4.3    | ~ 13.2     | V    |
|                      | $PV_{CC1}$ | 4.3    | ~ $V_{CC}$ | V    |
|                      | $PV_{CC2}$ | 4.3    | ~ $V_{CC}$ | V    |

● Electrical characteristics (Unless otherwise noted; Ta=25°C, Vcc=12V, PVcc1=PVcc2=5V, BIAS=2.5V, RL=8Ω, Rd=0.5Ω, C=100pF)

| Parameter                      | Symbol              | Min. | Typ. | Max. | Unit | Conditions                 |
|--------------------------------|---------------------|------|------|------|------|----------------------------|
| Quiescent current              | I <sub>CC</sub>     | —    | 18   | 27   | mA   |                            |
| Stand-by quiescent current     | I <sub>ST</sub>     | —    | —    | 0.5  | mA   |                            |
| Voltage for stand-by ON        | V <sub>STON</sub>   | —    | —    | 0.5  | V    |                            |
| Voltage for stand-by OFF       | V <sub>STOFF</sub>  | 2.0  | —    | —    | V    |                            |
| <Actuator driver>              |                     |      |      |      |      |                            |
| Output offset voltage          | I <sub>OO</sub>     | −6   | —    | 6    | mV   |                            |
| Maximum output amplitude       | V <sub>OM</sub>     | 3.6  | 4.0  | —    | V    |                            |
| Trans conductance              | g <sub>m</sub>      | 1.3  | 1.5  | 1.7  | A/V  | V <sub>IN</sub> =BIAS±0.2V |
| <Sled motor driver/Pre OP-amp> |                     |      |      |      |      |                            |
| Common mode input range        | V <sub>ICM</sub>    | −0.3 | —    | 11.0 | V    |                            |
| Input bias current             | I <sub>BOP</sub>    | —    | 30   | 300  | nA   |                            |
| Low level output voltage       | V <sub>OLOP</sub>   | —    | 0.1  | 0.3  | V    |                            |
| Output source current          | I <sub>SO</sub>     | 0.3  | 0.5  | —    | mA   |                            |
| Output sink current            | I <sub>ST</sub>     | 1    | —    | —    | mA   |                            |
| <Sled motor driver>            |                     |      |      |      |      |                            |
| Output offset voltage          | V <sub>OOFSL</sub>  | −100 | 0    | 100  | mV   |                            |
| Maximum output voltage         | V <sub>OMLD</sub>   | 7.5  | 9.0  | —    | V    |                            |
| Closed loop voltage gain       | G <sub>VSL</sub>    | 18.0 | 20.0 | 22.0 | dB   | V <sub>IN</sub> =±0.2V     |
| <Loading motor driver>         |                     |      |      |      |      |                            |
| Output offset voltage          | V <sub>OOFSLD</sub> | −50  | 0    | 50   | mV   |                            |
| Maximum output voltage         | V <sub>OMLD</sub>   | 3.6  | 4.0  | —    | V    |                            |
| Closed loop voltage gain       | G <sub>VLD</sub>    | 13.5 | 15.5 | 17.5 | dB   | V <sub>IN</sub> =BIAS±0.2V |
| Gain error by polarity         | ΔG <sub>VLD</sub>   | 0    | 1    | 2    | dB   | V <sub>IN</sub> =BIAS±0.2V |

This product is not designed for protection against radioactive rays.

● Application Circuit



### Notes

- No technical content pages of this document may be reproduced in any form or transmitted by any means without prior permission of ROHM CO.,LTD.
- The contents described herein are subject to change without notice. The specifications for the product described in this document are for reference only. Upon actual use, therefore, please request that specifications to be separately delivered.
- Application circuit diagrams and circuit constants contained herein are shown as examples of standard use and operation. Please pay careful attention to the peripheral conditions when designing circuits and deciding upon circuit constants in the set.
- Any data, including, but not limited to application circuit diagrams information, described herein are intended only as illustrations of such devices and not as the specifications for such devices. ROHM CO.,LTD. disclaims any warranty that any use of such devices shall be free from infringement of any third party's intellectual property rights or other proprietary rights, and further, assumes no liability of whatsoever nature in the event of any such infringement, or arising from or connected with or related to the use of such devices.
- Upon the sale of any such devices, other than for buyer's right to use such devices itself, resell or otherwise dispose of the same, no express or implied right or license to practice or commercially exploit any intellectual property rights or other proprietary rights owned or controlled by
- ROHM CO., LTD. is granted to any such buyer.
- Products listed in this document use silicon as a basic material.  
Products listed in this document are no antiradiation design.

The products listed in this document are designed to be used with ordinary electronic equipment or devices (such as audio visual equipment, office-automation equipment, communications devices, electrical appliances and electronic toys).

Should you intend to use these products with equipment or devices which require an extremely high level of reliability and the malfunction of which would directly endanger human life (such as medical instruments, transportation equipment, aerospace machinery, nuclear-reactor controllers, fuel controllers and other safety devices), please be sure to consult with our sales representative in advance.

#### About Export Control Order in Japan

Products described herein are the objects of controlled goods in Annex 1 (Item 16) of Export Trade Control Order in Japan.

In case of export from Japan, please confirm if it applies to "objective" criteria or an "informed" (by MITI clause) on the basis of "catch all controls for Non-Proliferation of Weapons of Mass Destruction.